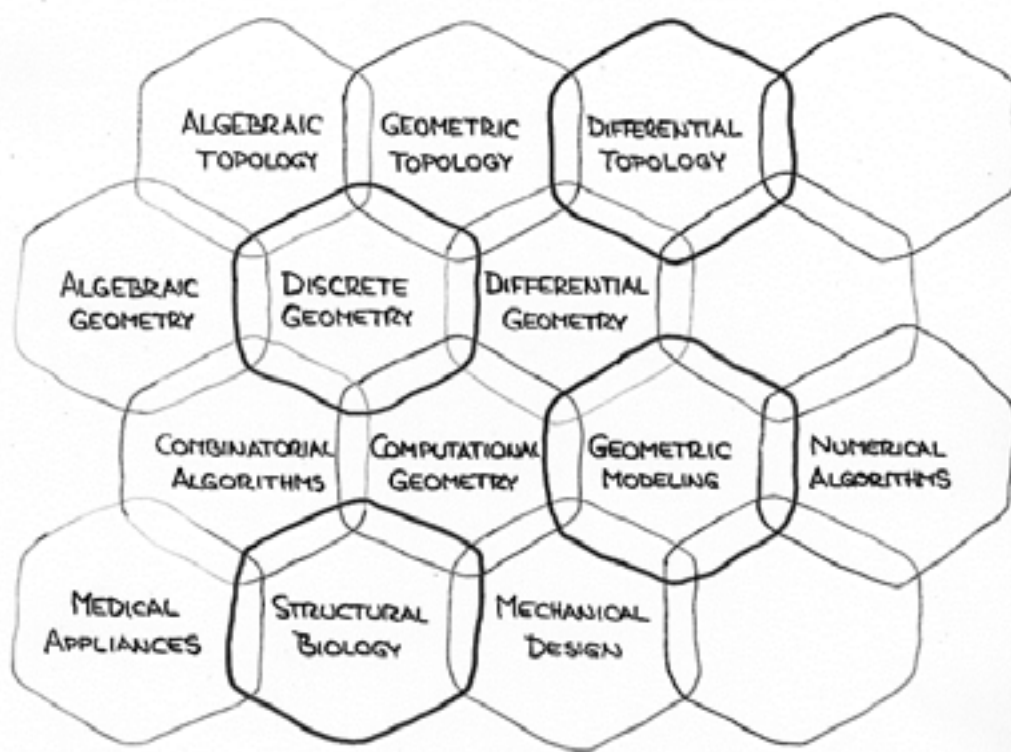


COMPUTATIONAL TOPOLOGY

APPLICATIONS-DRIVEN



HEARING-AIDS

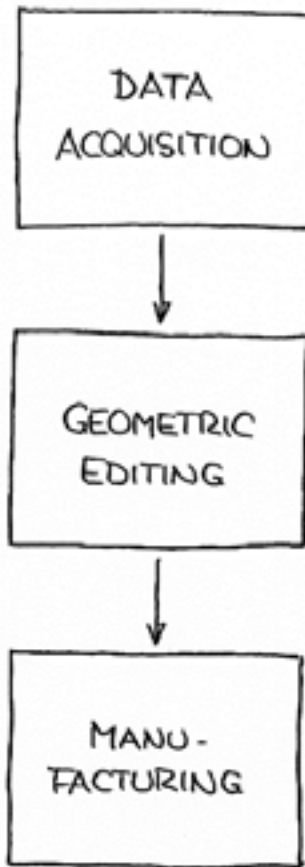
DRILLING + TRIMMING

ORTHODONTICS

SCANNING
SURFACE RECONSTRUCTION

FEATURE DETECTION
MOTION PLANNING

3D PRINTING

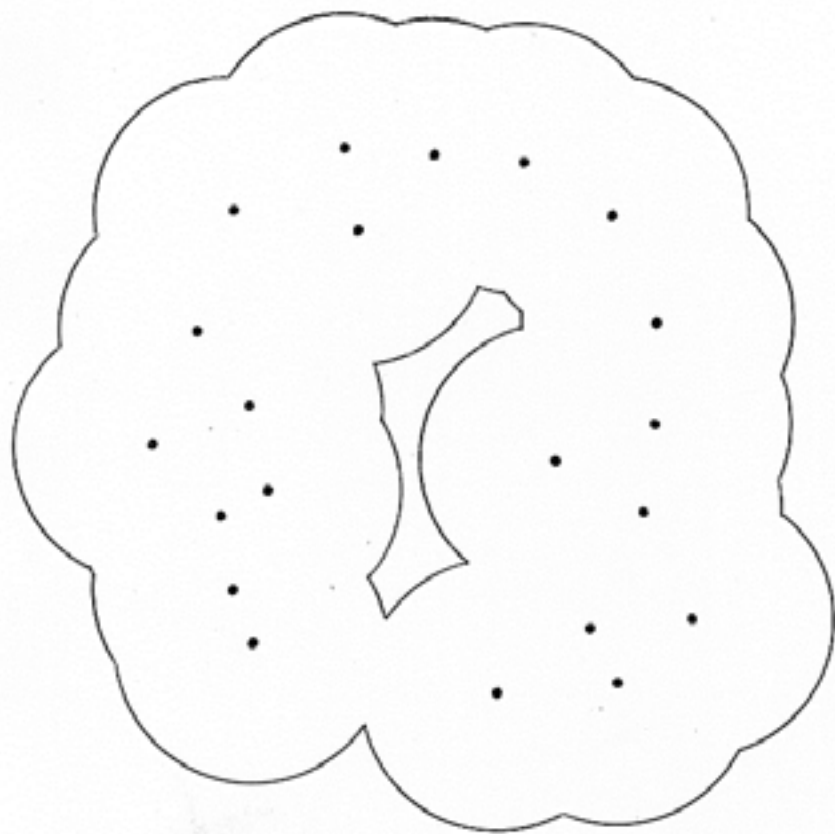


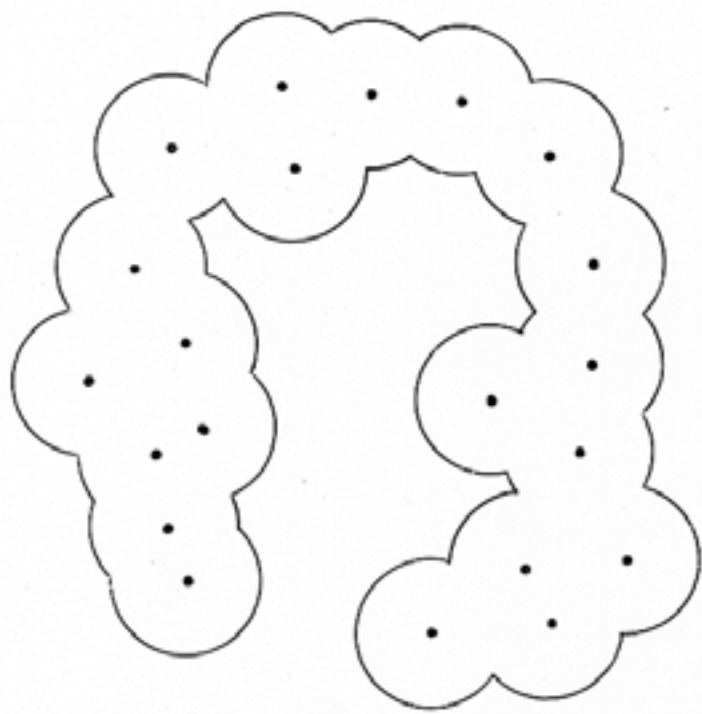
STRUCTURAL BIOLOGY

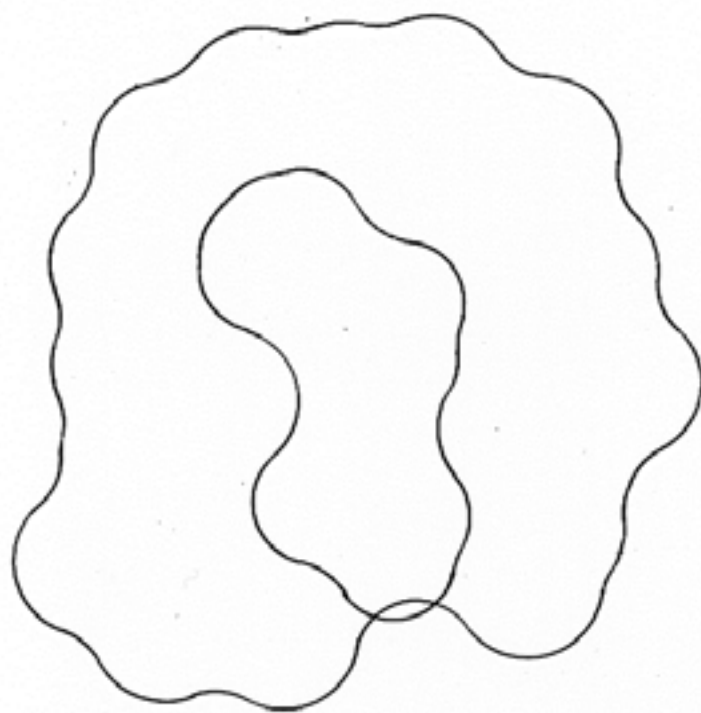
- I MODELS
 - II CONNECTIVITY
 - III SIZE
 - IV SHAPE AND FIT
 - V METAMORPHOSIS
-

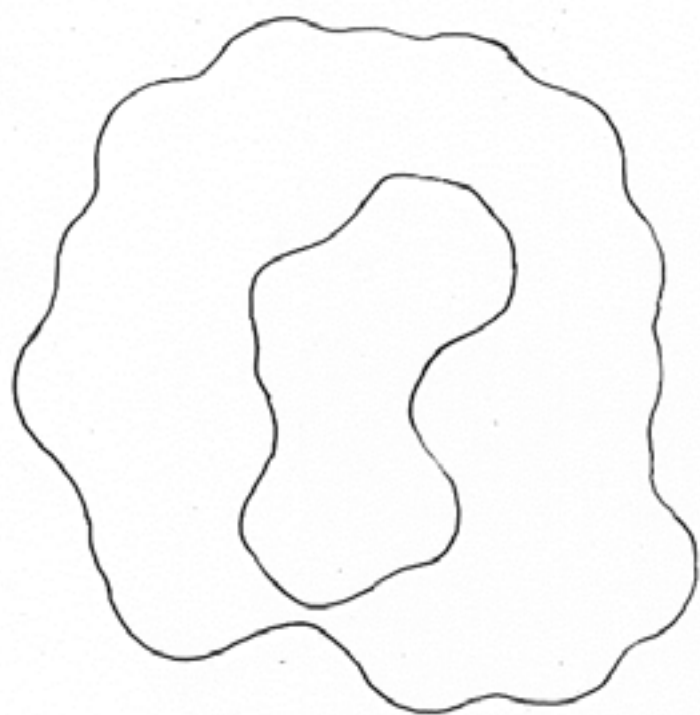
I MODELS

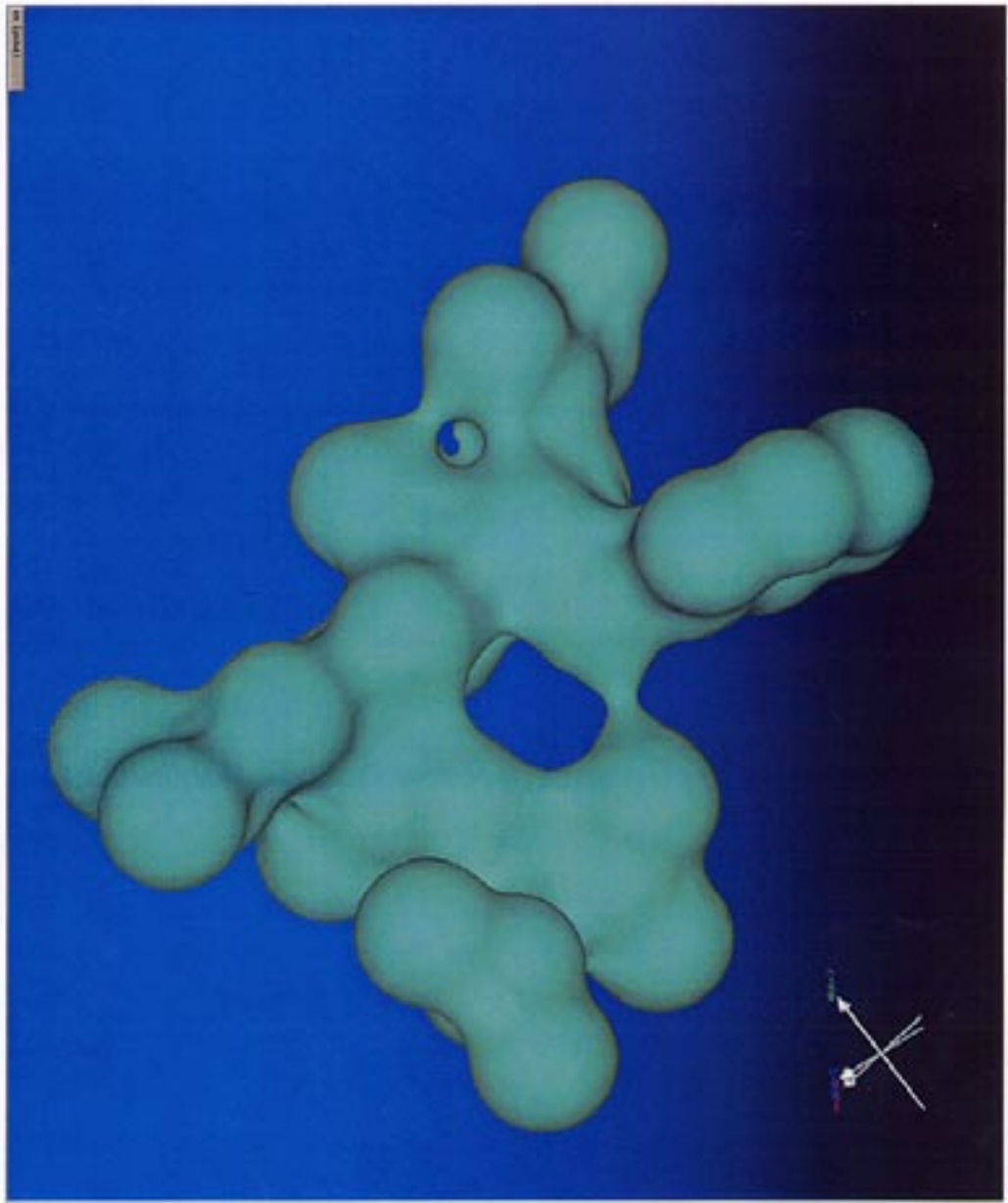
- (a) VAN DER WAALS
- (b) SOLVENT ACCESSIBLE
- (c) MOLECULAR SURFACE
- (d) VORONOI, DELAUNAY
- (e) ALPHA SHAPE
- (f) SKIN SURFACE

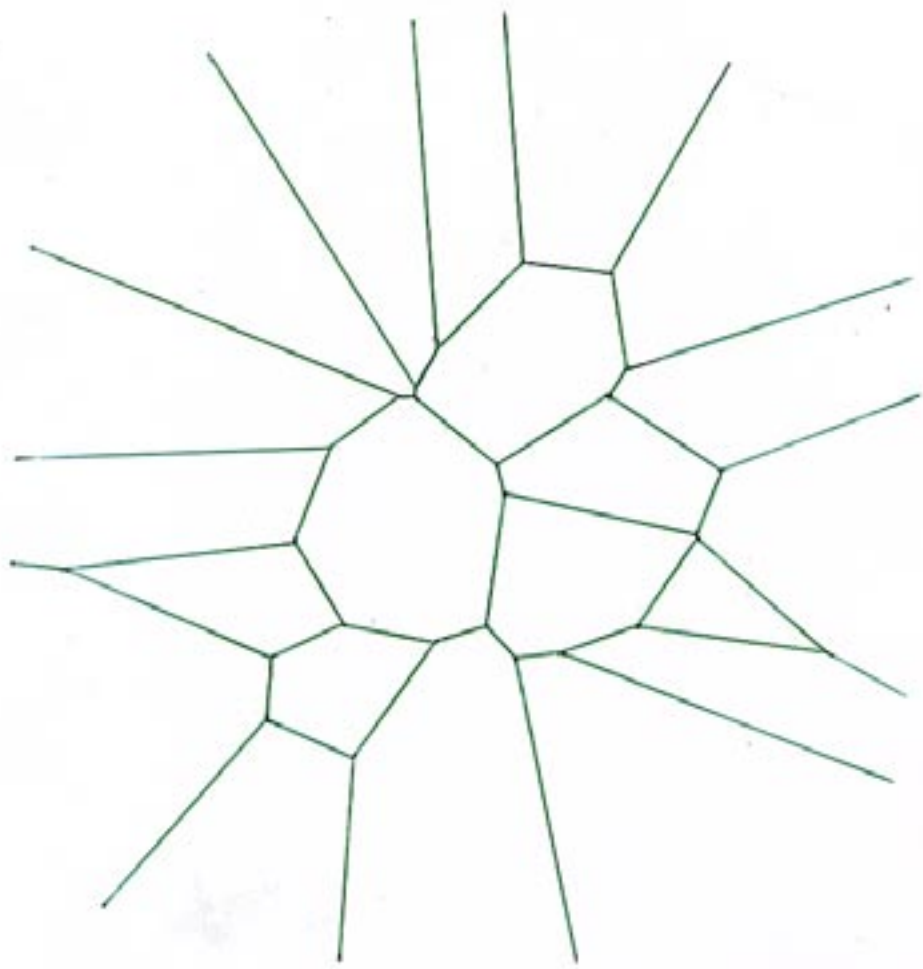


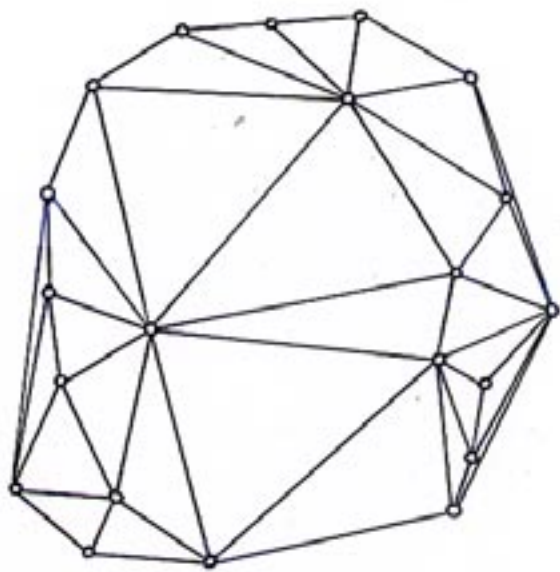




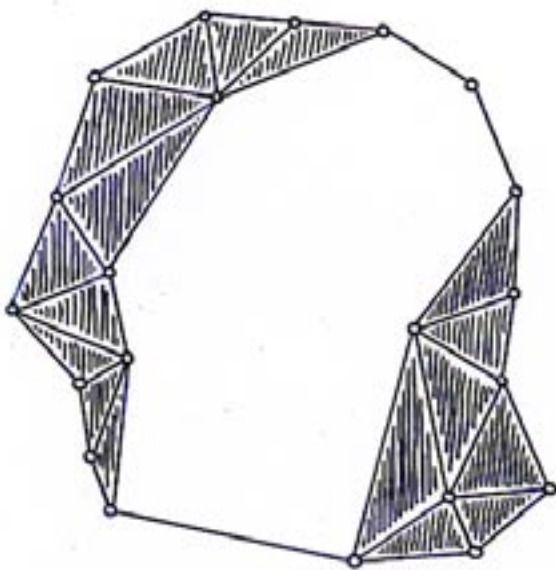


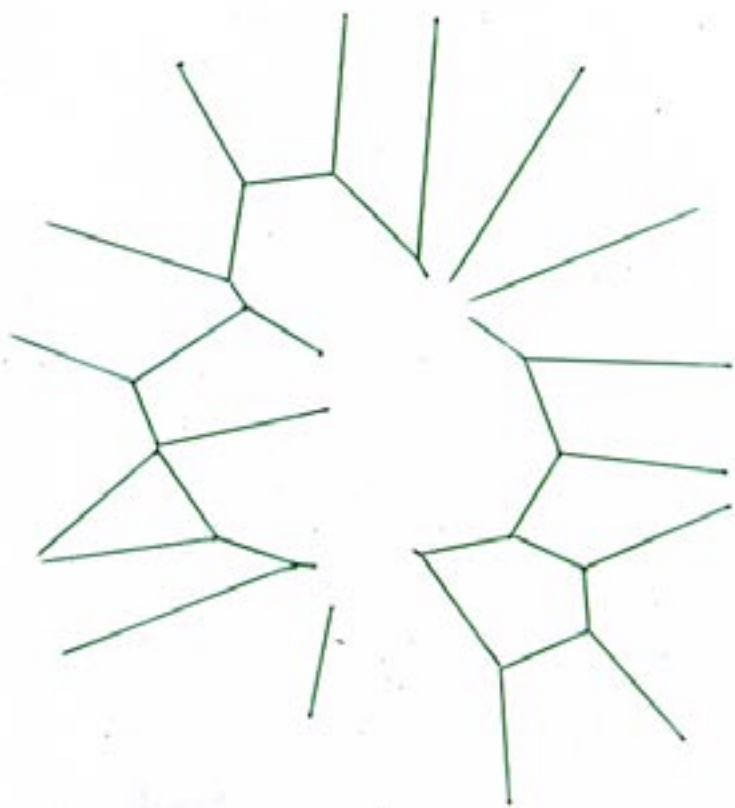


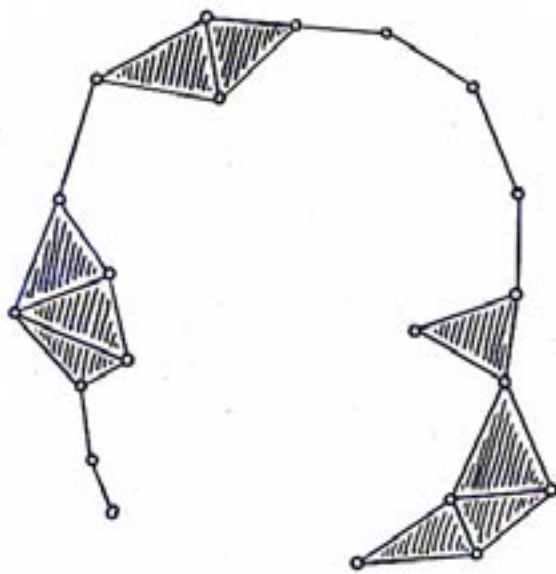












II. CONNECTIVITY

(a) HOMOTOPY EQUIVALENCE :

$$UB \cong |K|.$$

(b) BETTI NUMBER ALGORITHM.

(c) POCKETS.

(d) PERSISTENCE

$$\underbrace{\sigma_0, \sigma_1, \dots, \sigma_{j-1}, \sigma_j}_{= K = K_j} \quad \underbrace{\sigma_{j+1}, \dots, \sigma_n}_{= D-K}$$

FILTER: EVERY PREFIX IS A COMPLEX

$$K_0, K_1, \dots, K_{j-1}, K_j, K_{j+1}, \dots, K_n$$

FILTRATION $(K_i = \{\sigma_0, \sigma_1, \dots, \sigma_i\})$

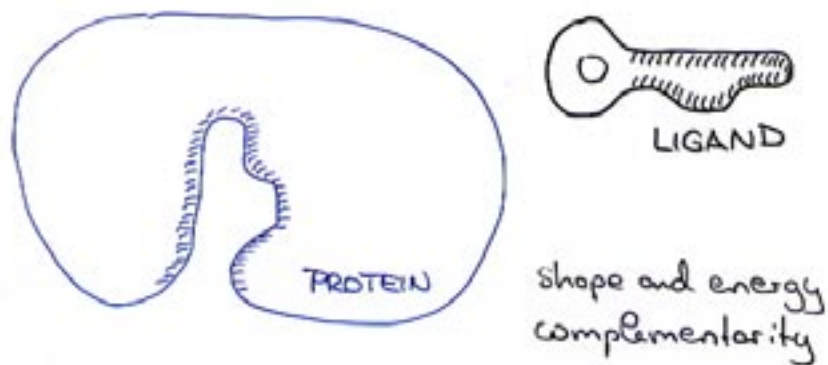
ALGORITHM FOR BETTI NUMBERS

```
integer3 BETTI ( $K_j$ ):  
   $\beta_0 = \beta_1 = \beta_2 = 0$ ;  
  for  $i = 0$  to  $j$  do  
     $k = \dim \sigma_i$  ;  
    if  $\sigma_i$  belongs to  $k$ -cycle in  $K_i$   
      then  $\beta_k ++$   
      else  $\beta_{k-1} --$   
    endif  
  endfor ;  
  return  $(\beta_0, \beta_1, \beta_2)$ .
```

TIME = $O(n \cdot \alpha(n))$.

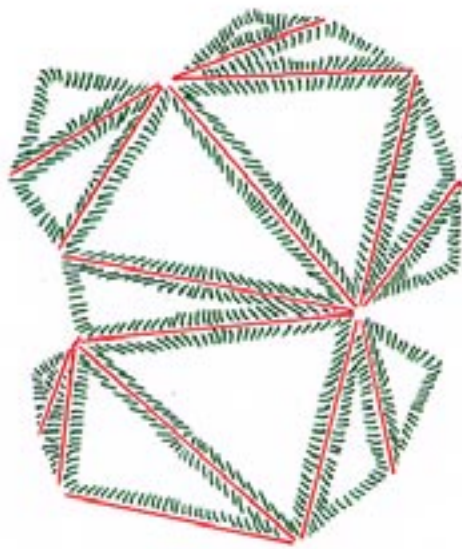
POCKETS (CAVITIES)

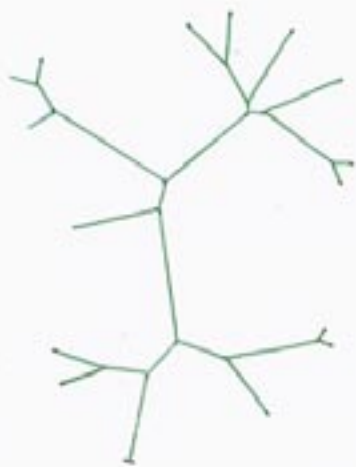
RECOGNITION BY COMPLEMENTARITY
(lock and key mechanism)



A **pocket** is a connected region outside
U_A; that becomes a void before it disappears.





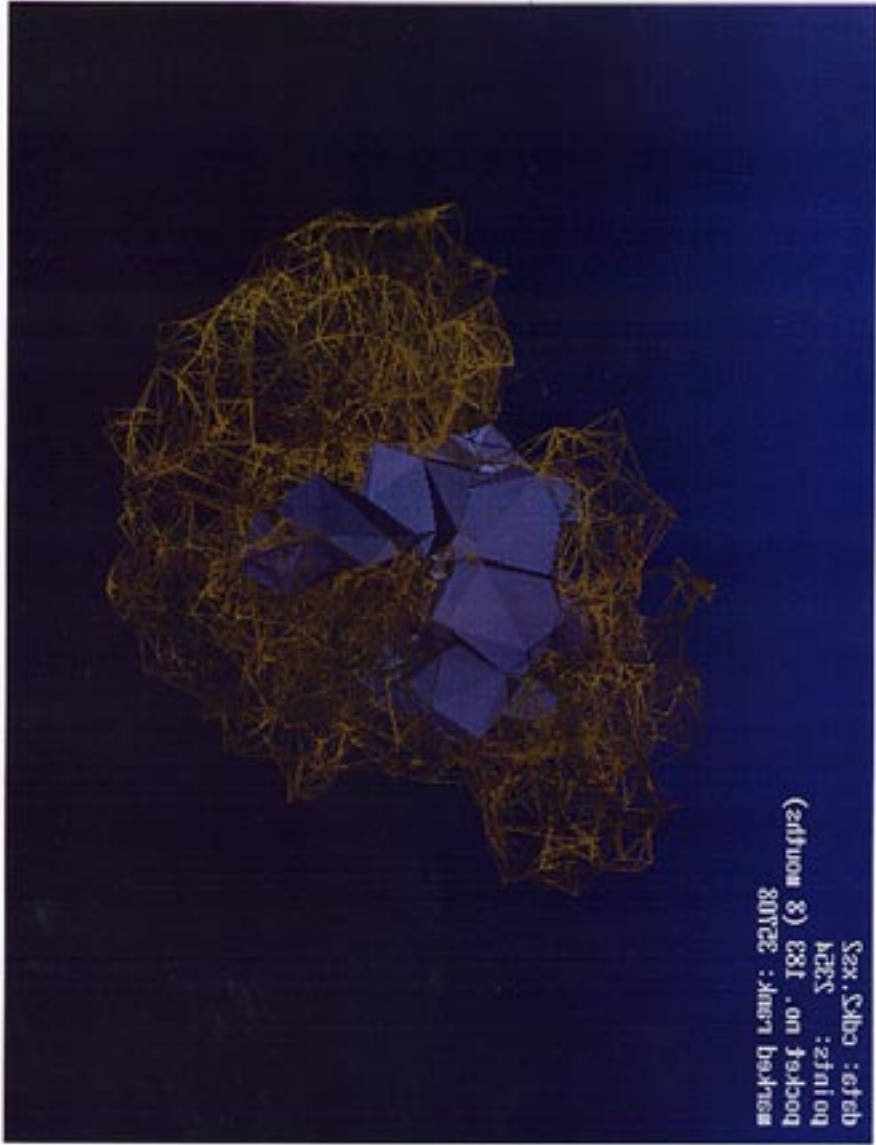






1

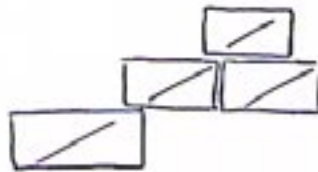
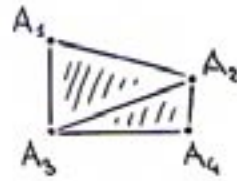




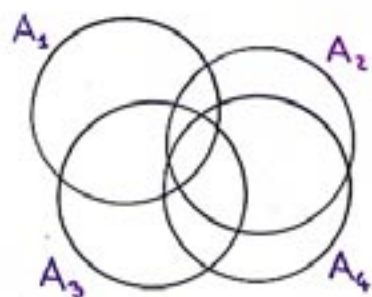
Sex: Skbo : eteb
kqey : zfnioq
(zfnioq 8) 181. on fskooq
80Yce : kneri baxnem

III. SIZE

- (a) PIE FORMULA
- (b) VOID FORMULA
- (c) AREA DERIVATIVE



THM. $\text{area } \cup_i A_i = \sum_{S \in \mathcal{K}} (-1)^{\dim S} \cdot \text{area } \cap S$



$$\begin{aligned}
 \text{area } \bigcup_i A_i &= A_1 + A_2 + A_3 + A_4 \\
 &\quad - A_{12} - A_{13} - A_{14} - A_{23} - A_{24} - A_{34} \\
 &\quad + A_{123} + A_{124} + A_{134} + A_{234} \\
 &\quad - A_{1234} .
 \end{aligned}$$

DEPTH - 2 FORMULA (AND VOIDS)

THM. $\text{area } U_i A_i = \sum_{\sigma^2 \in K} \text{area } \sigma^2$

$$+ \sum_{\substack{\sigma \in \tau \\ \sigma \in K}} (-1)^{\dim \sigma} \cdot \varphi_{\sigma, \tau} \cdot \text{area } \sigma.$$

angle at σ inside τ



AREA DERIVATIVE :

THE DERIVATIVE OF THE AREA OF UB
IS

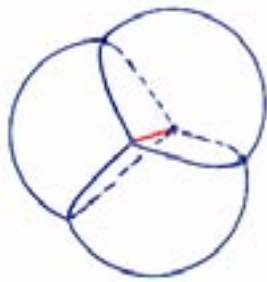
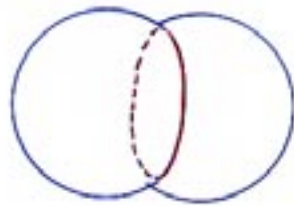
$$DA_B : \mathbb{R}^{3n} \rightarrow \mathbb{R}$$

DEFINED BY $DA_B(t) = \langle a, t \rangle$ WITH

$$\begin{bmatrix} a_{3i+1} \\ a_{3i+2} \\ a_{3i+3} \end{bmatrix} = \sum_j (\sigma_{ij} a_{ij} + \sum_k \beta_{ijk} a_{ijk}),$$

$$a_{ij} = \pi(p_i + p_j) \left[1 - \frac{(p_i - p_j)^2}{z_{ij}^2} \right] u_{ij}$$

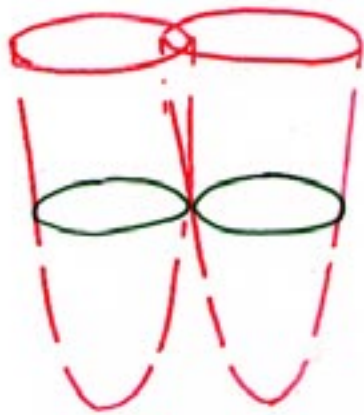
$$a_{ijk} = 2 p_{ijk} \frac{p_i - p_j}{z_{ij}} u_{ijk}$$





IV SHAPE & FIT

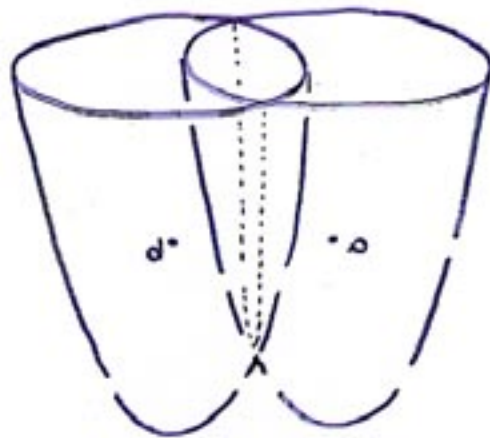
- (a) VECTOR SPACE
- (b) BODY & SKIN
- (c) SYMMETRY





$$\langle \omega \rangle^t (g_j + f_x) = \delta_j + A x \quad s_j - s \| \omega - x \| = \langle \omega \rangle g_j + f_x$$

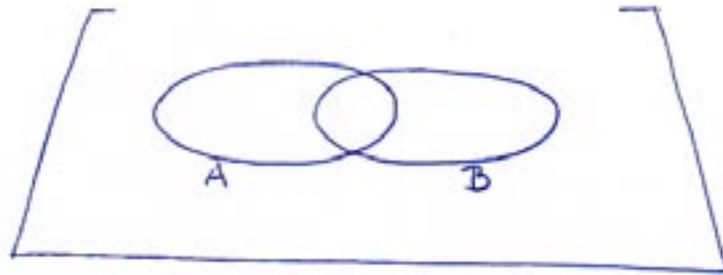
$$0 \leq \delta_j, x, t = g_j + x \text{ Ntic}$$

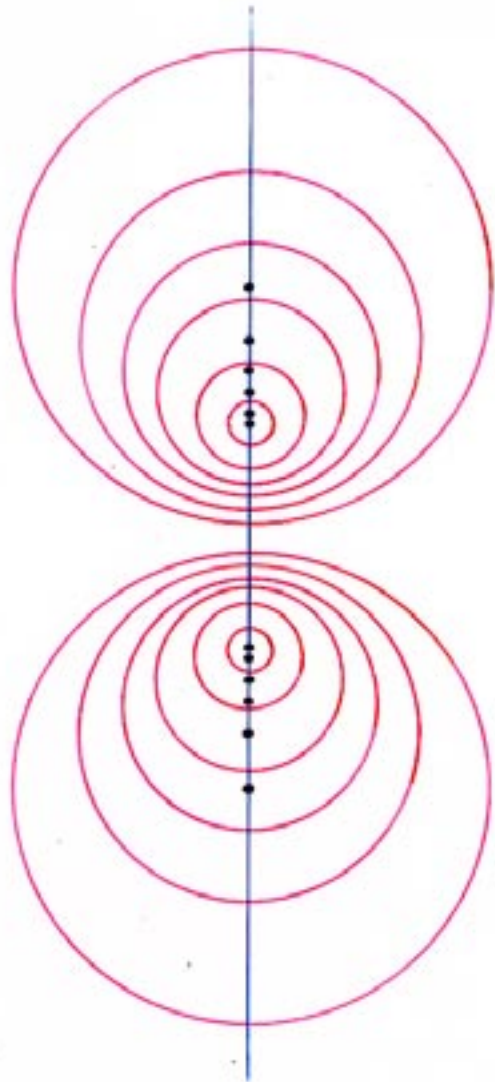


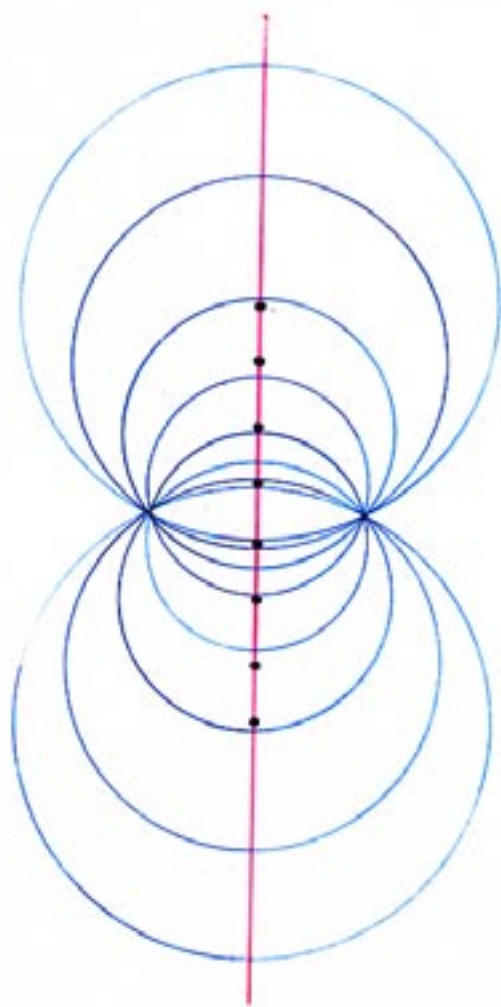
$$\begin{aligned} (o)^{1-7} &= A \\ (o)^{2-8} &= B \end{aligned}$$

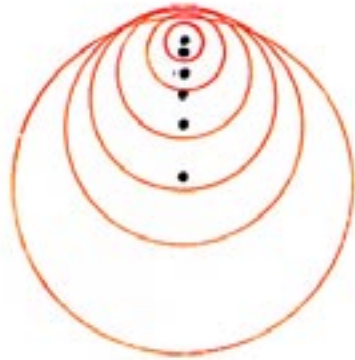
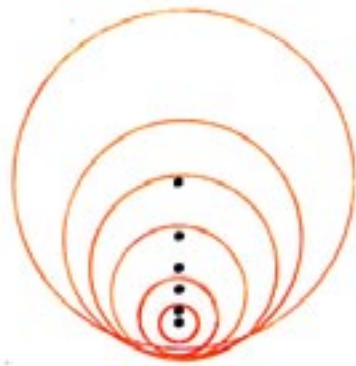
$$\begin{aligned} s_1 - s_1 \| a - x \| &= (x)^7 \\ s_2 - s_2 \| b - x \| &= (x)^8 \end{aligned}$$

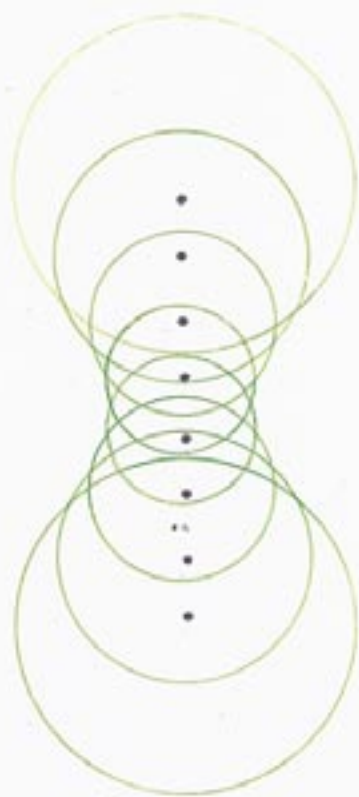
VECTOR SPACE OF CIRCLES

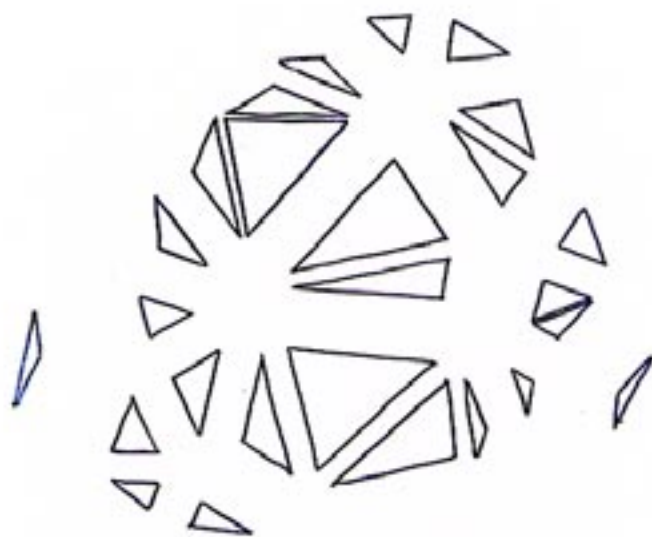


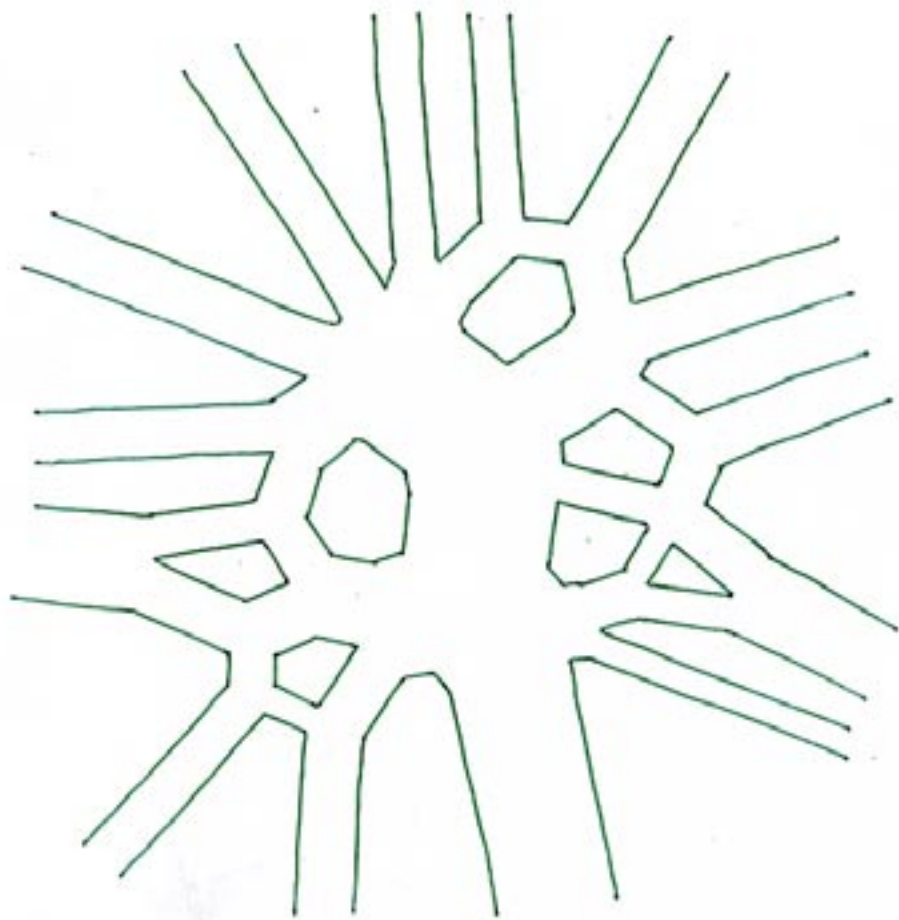


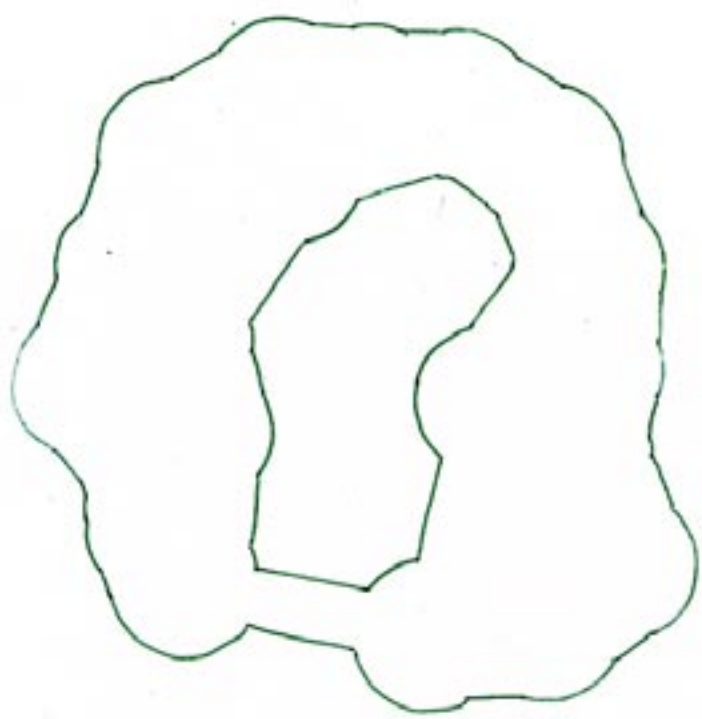


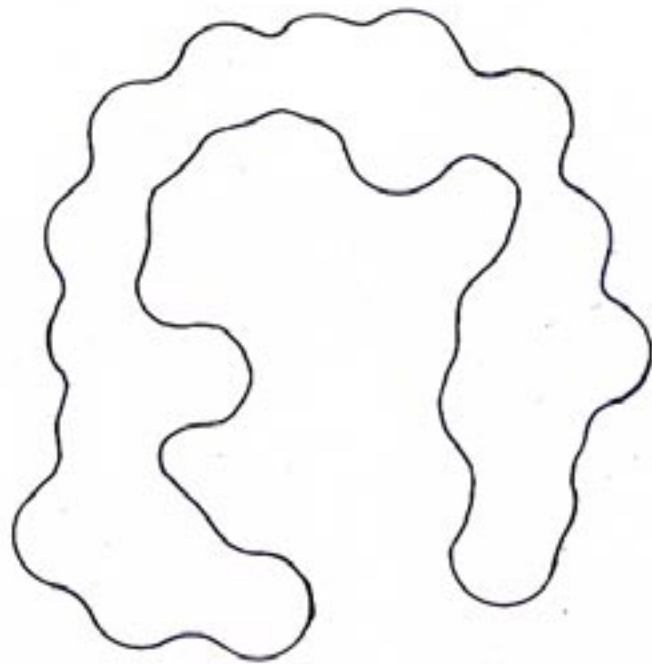






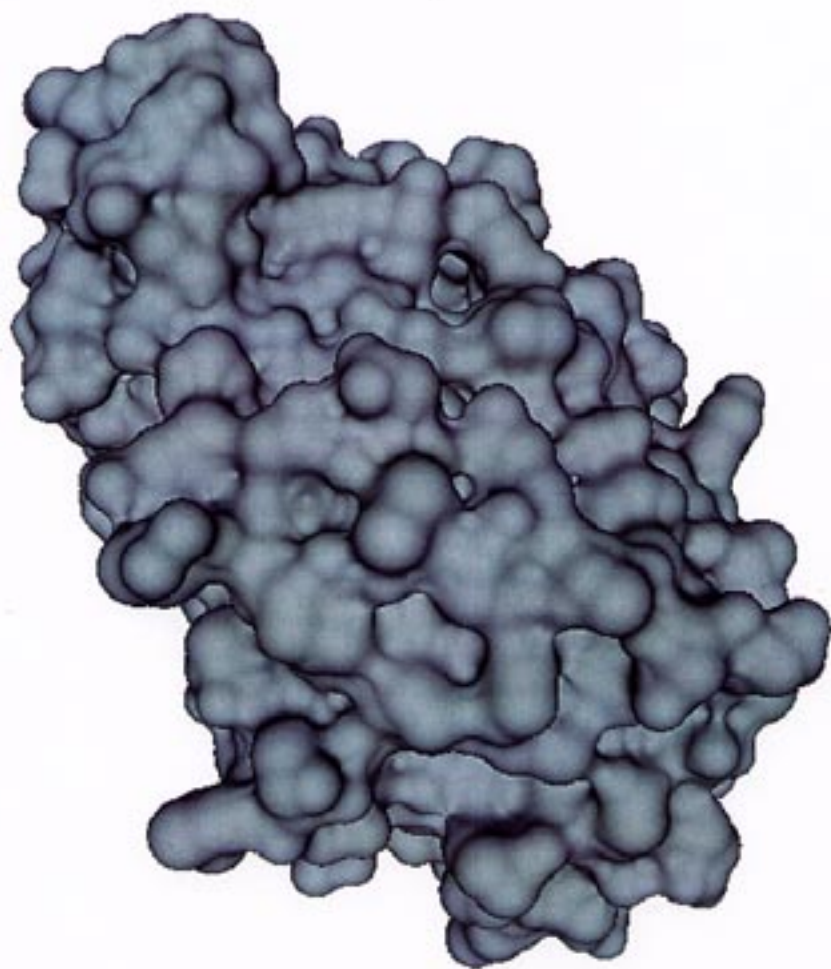


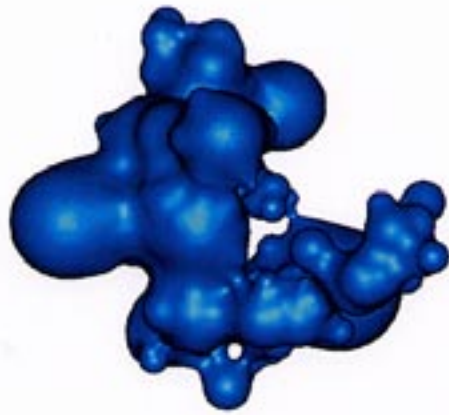
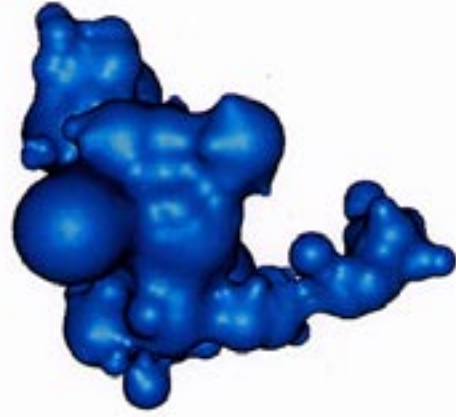













V. METAMORPHOSIS

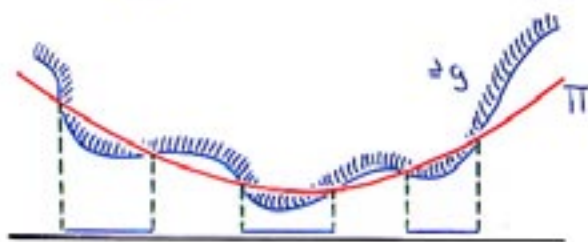
- (a) MIXED VOLUME
 - (b) DYNAMIC MESHING
 - (c) TOPOLOGY OPTIMIZATION
- 

GEOMETRIC CONSTRUCTION

$$\text{shape}^d = \text{proj} [\text{conv}^{d+1} \cap \text{bd conv}^{d+1}].$$

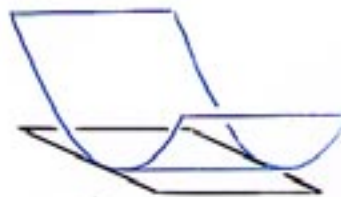
above graph of
 $g: \mathbb{R}^d \rightarrow \mathbb{R}$

graph of $\Pi: \mathbb{R}^d \rightarrow \mathbb{R}$
defined by $\Pi(x) = \|x\|^2$

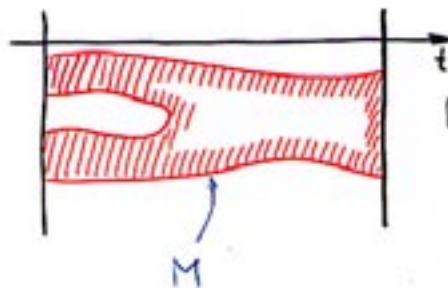
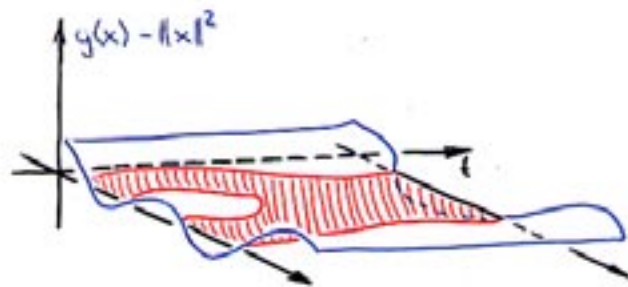


MAIN STEPS.

1. $X_0, X_1 \subseteq \mathbb{R}^d$ represented by
 $g_0, g_1: \mathbb{R}^d \rightarrow \mathbb{R}$
2. deformation through mixed
volume and sweep in
 $\mathbb{R}^{d+1} \times [0, 1]$.



MORSE THEORY INTERPRETATION

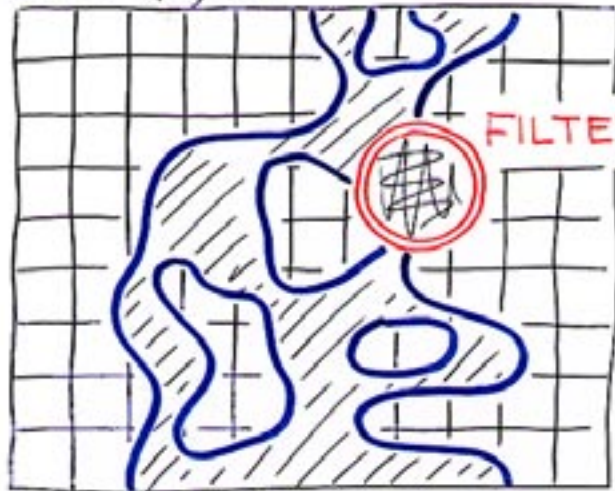


Morse function
 $f: M \rightarrow \mathbb{R}$
 $f(x) = t$

shapes are $f^{-1}(t)$.
topology changes at critical points.

TOPOLOGY OPTIMIZATION

GRID (physics)



FILTER (avg.)

SKIN (geometry)

3D EXTRUSION BRIDGE DIE } DESIGN
INJECTION MOLD }
MEMS }

ADAPTATION

TO SHAPE

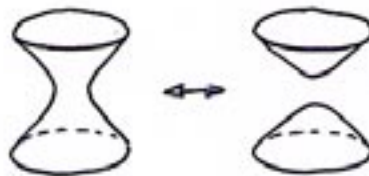
e.g. move vertices
along gradient

TO CURVATURE

mesh density $\sim \frac{1}{\text{max curvature function}}$

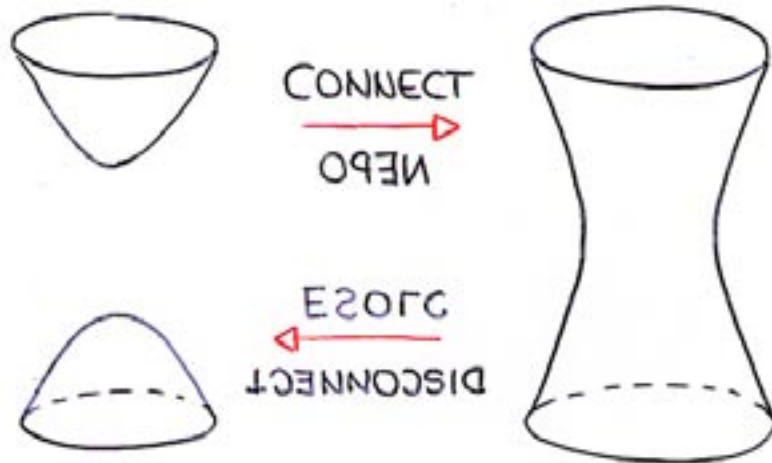
e.g. maintained through
point insertions and edge contractions

TO TOPOLOGY



TOPOLOGY

(HANDLES & TUNNELS)



TOPOLOGY

(COMPONENTS & VOIDS)

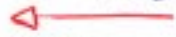
\emptyset

CREATE

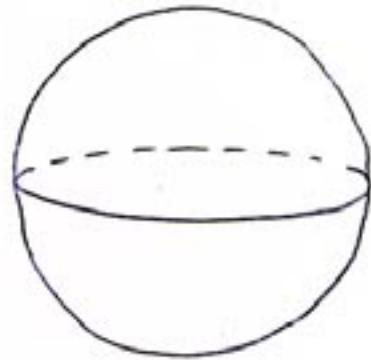


HOLLOW

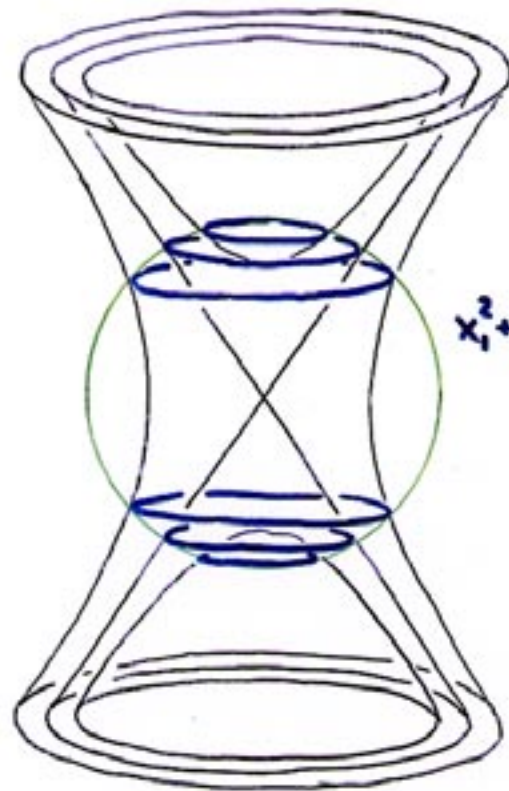
FILL



DISTROY



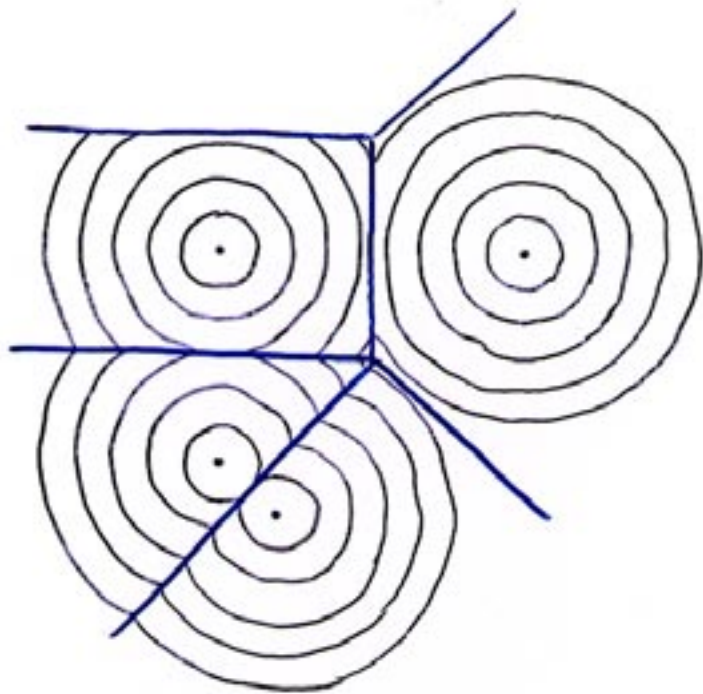
ISO CURVATURE



$$x_1^2 + x_2^2 + x_3^2 = r^2$$

$$x_1^2 + x_2^2 - x_3^2 = \text{const.}$$

CURVATURE VARIATION



$$\left| \frac{1}{\kappa(x)} - \frac{1}{\kappa(y)} \right| \leq \|x - y\|$$

III.3 DENSITY

